## FIG.1A

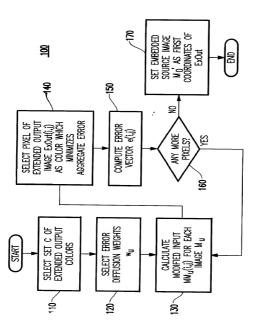


FIG.1B



FIG.2A

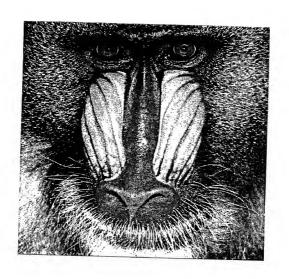


FIG.2B



FIG.2C

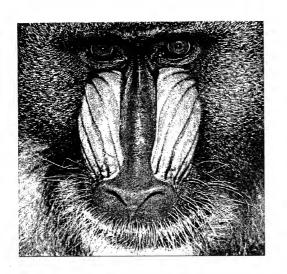
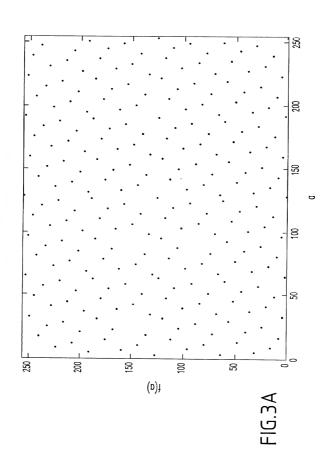


FIG.2D



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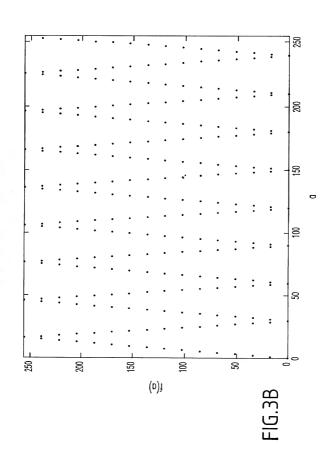




FIG.4A

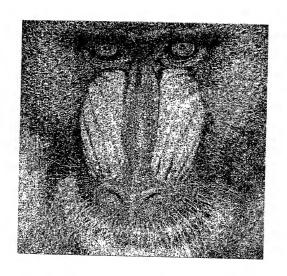


FIG.4B

```
/* iteration */
     For each iteration
                                              /* rows */
         for each i
             for each j
                                             /* column */
                  for each member d of C /* search through
                                              all possible members
5
                                              of C */
                     set ExOut(i,j) = d
                      compute
                         v(d) = |L(ExOut_0 - M_0)|^2 + |L(PExOut_1 - M_0)|^2
                  endfor (d)
10
                 set ExOut(i,j) = \underset{d}{argmin} v(d)
              endfor (i)
         endfor (i)
     endfor (iteration) or until ExOut has not changed
     between two consecutive iterations.
15
     Set embedded source image M_0' as the first
```

FIG.5A

coordintes of ExOut.

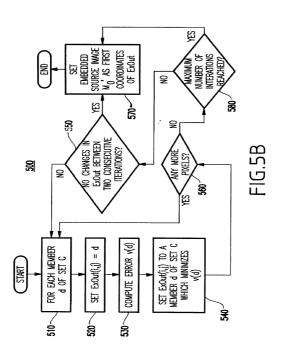




FIG.6A



FIG.6B

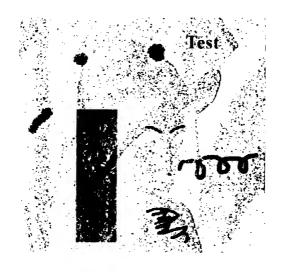


FIG.6C



FIG.6D



FIG.6E

